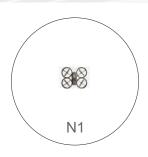
OPDW / S20 / Soldier Recon



\$20 is a mid-size utility sUAS in PDW's family of small autonomous platforms designed for the modern warfighter.

A small man-packable sUAS designed for maximum utility and versatility. S20 supports organic ISR and strike operations with hot-swappable payloads, open architectures, and hands-free autonomy features. Fully functional in zero light, S20 is a versatile workhorse made to traverse indoor and outdoor environments in any weather scenario. Shares common design in electronics and software with PDW's C100 and N1 platforms for advanced operations and multi-sUAS deployments.







OPDW / S20 / Soldier Recon

\$20 ships with a high-quality FLIR EO/IR gimbal payload and Blue-UAS approved avionics package. Functional in any environment, including zero light or GPS denied, with vision-based flight guidance. Edge computing and a suite of autonomy features ease cognitive burden and provide hands-free functionality. Ruggedized IP54 design folds into a small wearable pouch with field-replaceable arms and propellors.



Zero-Light Vision Navigation

S20 offers flight guidance & collision avoidance for nighttime, tactical missions in GPS-denied environments.



Open Architecture

For application or payload development, S20's modular architecture supports any present or future technologies and missions.



Edge Computing

DIU Blue-UAS approved (ModalAI) flight avionics with Qualcomm Snapdragon 812.



Flight Endurance

35+ mins of flight time for missions requiring extended range or loitering endurance.



Universal Payload

Picatinny rail supports up to 750g of additional payload.



EO/IR Gimbal Payload

2-axis stabilized gimbal provides seamless high-quality EO/IR video for day or night missions.



Durable

Field replaceable arms, propellers, and antennas designed for variable environments.

prevention. With on-board edge computer, features list is upgradable as developed.



and secure communication.

AES-256 encrypted link for reliable Provides object detection, visual inertial odometry, and vision-based collision

